



Dedicated Protection Scheme with Availability Guarantee

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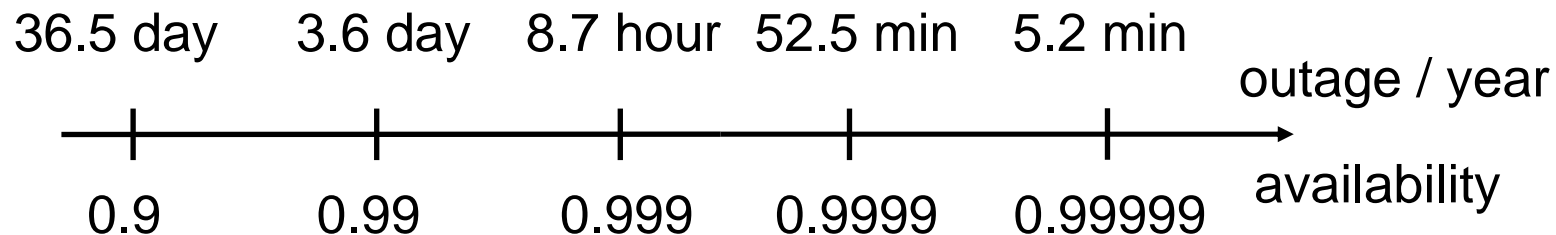
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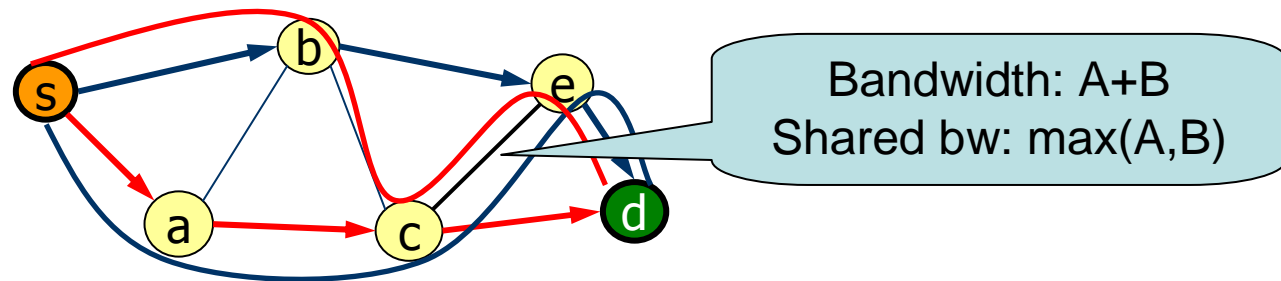
End-to-End Service Availability Guarantee

- Using only one path in the network (called **working path**) for sending user's data may not suffice high availability requirements
- Using more paths (called **protection path(s)**)
 - High availability is reachable
 - Using resources in an economic way

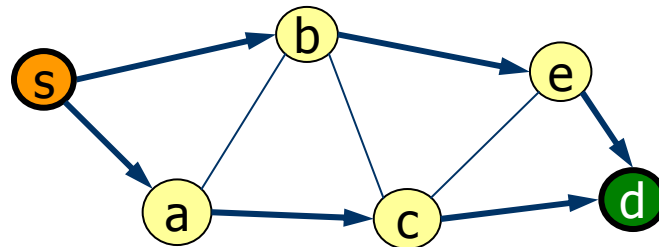


Protection schemes in optical environment

- **Shared Protection** schemes are rarely installed by service providers because of their complexity



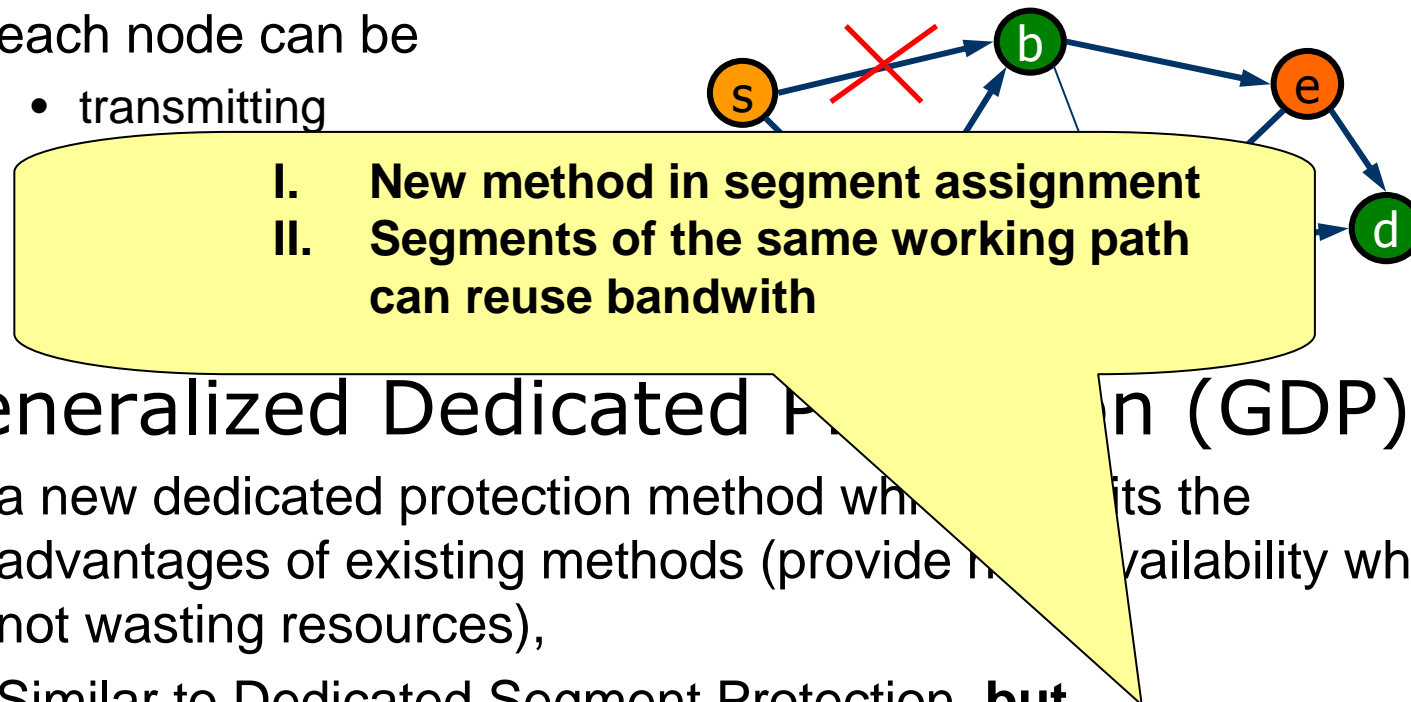
- **Dedicated Path Protection (DPP, 1+1)** schemes are often used because of their simplicity, but they have limited availability guarantee abilities



Protection schemes in optical environment (2)

- **Dedicated Segment Protection** can guarantee a given availability level but wasting resources

- each node can be
 - transmitting



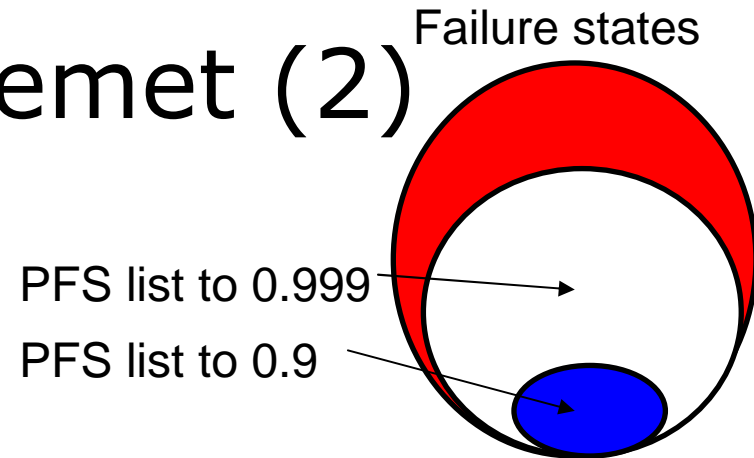
- **Generalized Dedicated Protection (GDP)**
 - a new dedicated protection method which inherits the advantages of existing methods (provide high availability while not wasting resources),
 - Similar to Dedicated Segment Protection, **but**

I. Segment assignemet

- Our segment assignemet is built on **failure dependencies** contrary with most of the existing methods
 - wrong router drags down some of the neighboring routers sending faulty packages
 - in case of conduit cut a great number of connections has failed at the same time
- A **long list** of network failures worked out by the service provider is given
- A **failure state (FS)** represents the current state of the network after one failure occured

I. Segment assignemet (2)

- A failure state contains the
 - failed network elements
 - stationary probability $P(x)$
 - In reality: measurements, a failure list is available
 - In paper: generating based on independent failure events
- A FS selected to protect a given availability level is a Protection Failure State (PFS)
 - when a connection protects a PFS, the $P(x)$ of the PFS can be added to it's availability
- For each provided availability class a **global list of PFS** is generated



II. Generalized Dedicated Protection Routing Problem (GDP-RP)

- **Given:**
 - $G(V,E)$ representing the GMPLS network topology, where for all $e \in E$ a c_e cost function is given
 - Source s and destination d node of the connection
 - C_g PFS list. For all $PFS_a \in C_g$ a $G_a(V,E_a)$ subgraph is given, where E_a denotes the edges PFS_a NOT contains
- **Find:**
 - A $H(V,E')$ subgraph in $G(V,E)$, that for all $G_a(V,E_a)$ PFS_a graph contains path between s and d
 - In this case the connection is available in all PFS state in C_g , which means the connection availability is at least g

II. GDP-RP Dijkstra heuristic

- The problem is NP hard
 - if the number of sub-graphs are part of the input
- A simple heuristic using shortest path search provides a decent performance

G_1

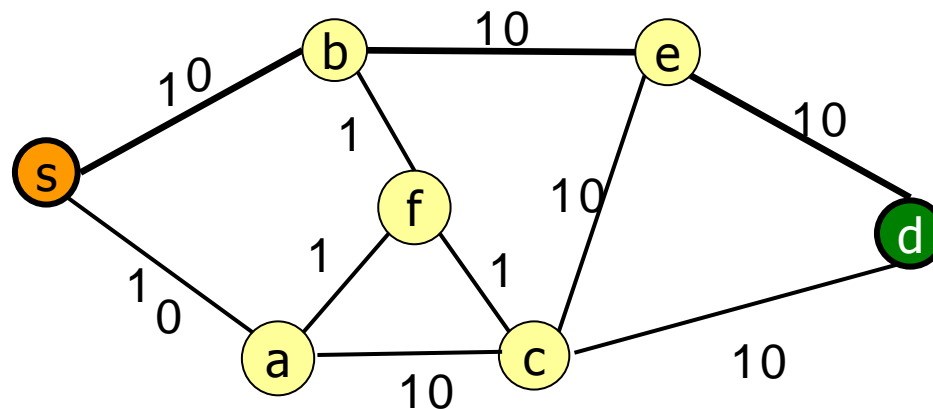
$PFS_1 = \{(s,b)\}$

G_2

$PFS_2 = \{(b,e), (c,d)\}$

G_3

$PFS_3 = \{(e,d)\}$

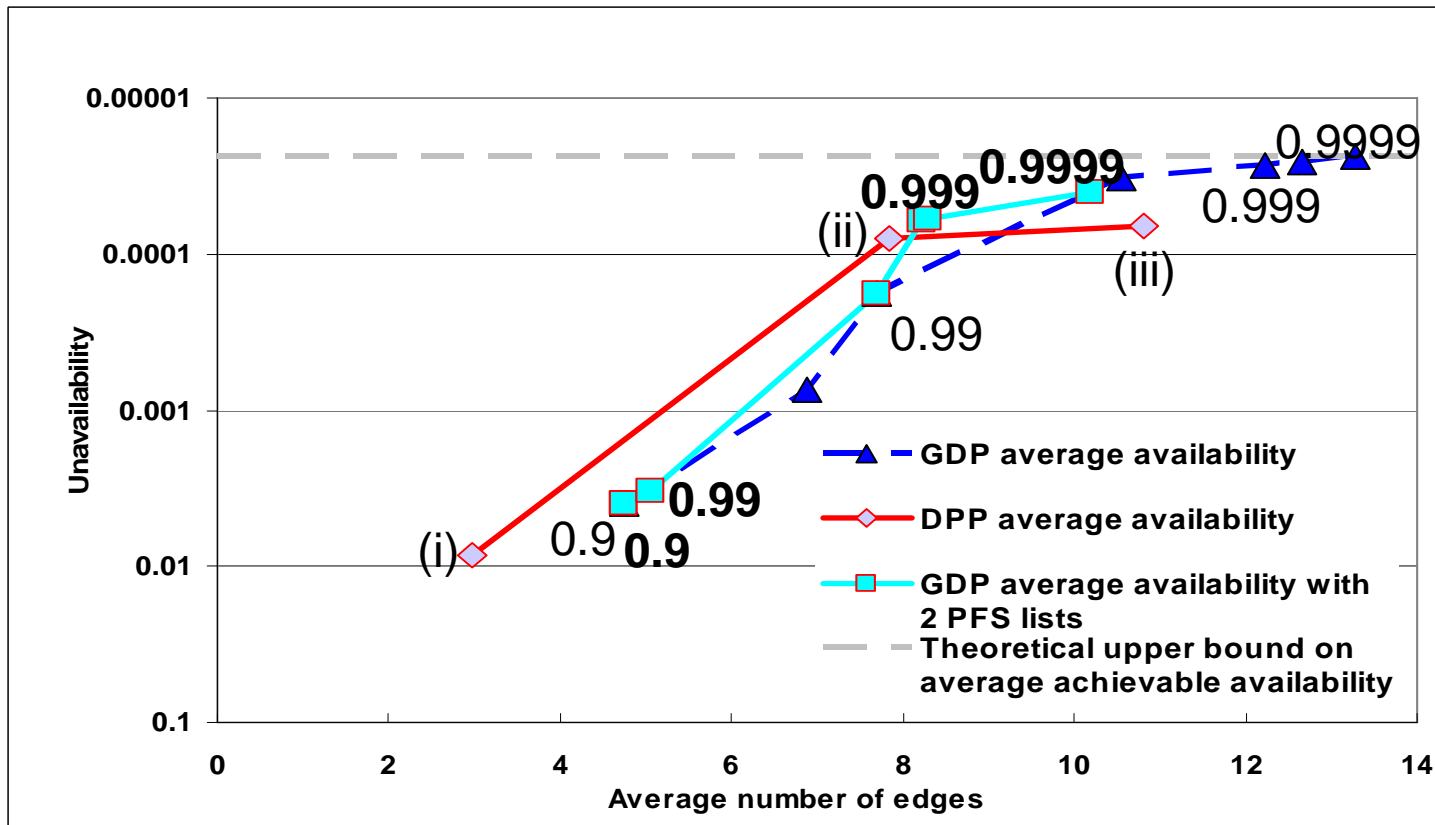


II. GDP-RP Dijkstra heuristic improvements

- Problems:
 1. The resulted subgraph depends on the order of \mathbf{G}_a $(\mathbf{V}, \mathbf{E}_a)$ PFS graphs
 2. As we use only one PFS list for each service class, some connections receive much higher availability than they payed
- Solutions
 1. Removing redundant edges (or run the heuristic more times with different graph order)
 2. Using more PFS lists per availability class

Simulation results

- 37 nodes, 114 directed edges
- 836 PFS in the 0.9999 availability list
- About 100 ms running time in average
- All connection receives guaranteed availability with GDP
- GDP performs even better in **reserved capacity** than 1+1+1 DPP



Conclusions

- Novel failure model based on provider observations on failure dependencies
- Novel framework of survivable routing methods was given
- The goal is to guarantee availability for each connection
 - Reaching the limitation of the topology
- Simple to implement
 - The simplest heuristic method provides a decent performance in backbone topologies